FP93 **Program Controller**

Instruction Manual (Detailed version)

Thank you for purchasing a Shimaden product. Please check that the delivered product is the correct item you ordered. Please do not begin operating this product before you read this instruction manual thoroughly and understand its contents.

"Notice"

Please ensure that this instruction manual is given to the final user of the instrument.

"Preface"

This instruction manual is meant for those who will be involved in the wiring, installation, operation and routine maintenance of the FP93. It describes matters to be attended to in handling the FP93, how to install it, wiring, its functions and operating procedure. Keep this manual at the work site while handling the instrument and follow the guidance provided herein.

SHIMADEN CO., LTD.

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1. Safety Rules

For matters regarding safety, potential damage to equipment and/or facilities, additional instructions and notes are indicated by the following headings.

↑ WARNING

This heading indicates hazardous conditions that could cause injury or death of personnel unless extreme caution is exercised.

⚠ CAUTION

This heading indicates hazardous conditions that could cause damage to equipment and/or facilities unless extreme caution is exercised.

Note

This heading indicates additional instructions and/or notes.

The mark 1 property represents a protective conductor terminal. Make sure to ground it properly.

MARNING

The FP93 Program Controller are control instruments designed for industrial use to control temperature, humidity and other physical values. Avoid using it for control of devices which may seriously affect the human life. When used, adequate and effective safety measures must be taken. No warranty is valid in the case of an accident arising from the use of this product without such safety measures.

MWARNING

- For using this instrument, house it in a control box or the like lest terminals should be in contact with a person.
- Don't draw out the instrument from the case. Don't let your hand or a conductive body in the case. It may lead to serious injury or death due to an electric shock.
- Make sure to ground protective conductor terminals.

ACAUTION

• To avoid damage to connected equipment, facilities or products due to a fault of the product, safety measures must be taken before usage, such as the installation of a fuse, an overheating protection device and the like. No warranty is valid in the case of an accident arising from the use of this product without such safety measures.

⚠CAUTION

- The Amark on the plate affixed to the instrument:
 - On the terminal nameplate affixed to the case of this instrument, the alert mark \triangle is printed. This is to warn you of the risk of electric shock which may result if the charger is touched while being energized.
- As a means to turn the power off, a switch or a breaker should be installed in the external power circuit to be connected to the power terminal of the instrument. Fix the switch or the breaker adjacently to the instrument in a position which allows it to be operated with ease, with an indication that it is a means of turning the power off. Use a switch or a breaker which meets the requirement of IEC60947.
- Fuse
 - Since the instrument does not have a built-in fuse, do not forget to install a fuse in the power circuit to be connected to the power terminal. A fuse should be positioned between a switch or a breaker and the instrument and mounted on the L side of the power terminal.

Fuse rating / characteristics: 250V AC 1A / medium lagged or lagged type.

Use a fuse which meets the requirement of IEC60127.

• Voltage / current of a load to be connected to the output terminal and the alarm terminal should be within a rated range.

Otherwise, the temperature will rise to reduce the life of product and/or to result in problems with the product.

Otherwise, the temperature will rise to reduce the life of product and/or to result in problems with the product. For rated voltage/current, see "9. Specifications" of this manual.

The output terminal should be connected with a device which meets the requirements of IEC61010.

- A voltage / current different from that of the input specification should not be applied to the input terminal. It may reduce the life of the product and/or result in problems with the product. For rated voltage / current, see "9. Specifications" of this manual.
- In the case of voltage or current input, the input terminal should be connected to a device which meets the requirement of IEC61010. The instrument is provided with a draft hole for heat discharge. Take care to prevent metal and other foreign matters from getting into it. Failure to do so may result in trouble with the instrument or may even cause a fire.
- Don't block the draft hole or allow dust or the like to stick to it. A rise in temperature or insulation failure may result in a reduction of the life of the product and/or problems with it or may cause a fire.

For spaces between installed instruments, refer to "3-3. External Dimensions and Panel Cutout."

- It should be noted that repeated tolerance tests against voltage, noise, surge, etc. may lead to deterioration of the instrument.
- Users are prohibited from remodeling the product or abnormal use of it.
- It takes 30 minutes to display the correct temperature after applying power to the Program Controller. (Therefore, turn the power on more than 30 minutes prior to the operation.)
- To ensure safety and maintain the functions of this device, do not disassemble this device. If this device must be disassembled for replacement or repair, contact your dealer.
- This device is designed for mounting on the panel. Only the instruments mounted on the front of the panel facing outward are of protection class of IP66. Do not use in any environment where water or solids in excess of IEC60529 may get inside or when the device is not facing the front.

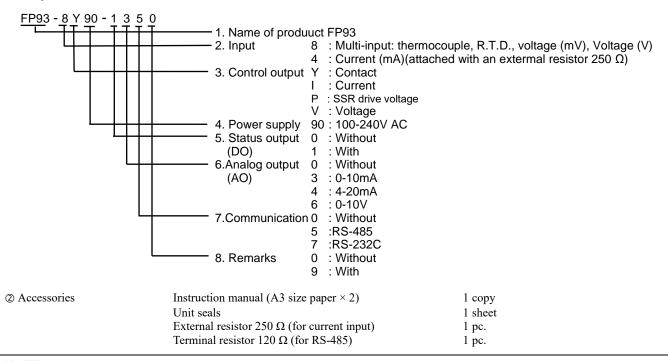
2. Introduction

2-1. Check before Use

This product has been fully inspected for quality assurance prior to shipment. Nevertheless, you are requested to make sure that there is no error, damage or shortage of delivered items by checking the model codes and the external view of the product and the number of accessories.
① Confirmation of Model Codes

Check the model codes stuck to the case of the product to ascertain if the respective codes designate what were specified when you ordered it, referring to the following code table:

Example of model codes:



NOTE: For any problem with the product, shortage of accessories or request for information, please contact our sales agent.

2-2. Handling Instruction

- ① Don't operate the keys on the front panel with a hard or sharply pointed object. Operate the keys only by softly touching them by your fingertips.
- ② When cleaning the instrument, wipe it gently with a dry cloth. Never use solvent such as a thinner.

3. Installation and Wiring

3-1. Installation Site (environmental conditions)

ACAUTION

This instrument should not be used in any of the places mentioned below. Selection of these places may result in trouble with the instrument, damage to it or even a fire.

- ① Where flammable gas, corrosive gas, oil mist and particles that can deteriorate electrical insulation are generated or abundant.
- ② Where the temperature is below -10 $^{\circ}$ C (14 $^{\circ}$ F) or above 50 $^{\circ}$ C (122 $^{\circ}$ F).
- 3 Where the relative humidity is above 90%RH or below dew point.
- Where highly intense vibration or impact is generated or transferred.
- So Near high voltage power lines or where inductive interference can affect the operation of the instrument.
- 6 Where the instrument is exposed to dew drops or direct sunlight.
- Where the height is above 2000 m.
- Outdoors.
- (9) Where the instrument is exposed to the flow of blowing air.

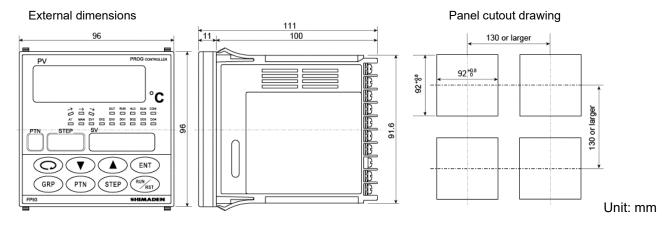
NOTE: The environmental conditions belong to the transient over voltage category II of IEC60664 and the degree of pollution is 2.

ACAUTION

For safety's sake and to protect the functionality of the product, don't draw out its body from the case. If it needs to be drawn out for replacement or repair, contact our sales agent.

- ① Cut a hole for mounting the controller in the panel by referring to the cutout drawing in Section 3-3.
- ② The panel thickness should be 1.0–4.0 mm.
- ③ As the instrument is provided with pawls for fixing, just press it firmly from the front of the panel. The case is fixed to the panel by means of the pawls.
- Be sure to install this product with the attached gasket. Failure to do so could result in electric shock. After wiring, do not touch terminal elements or other charged parts. Failure to do so could result in electric shock.
- ⑤ The FP93 is designed as a panel-mounting model. Never use it without mounting on the panel.

3-3. External Dimensions and Panel Cutout

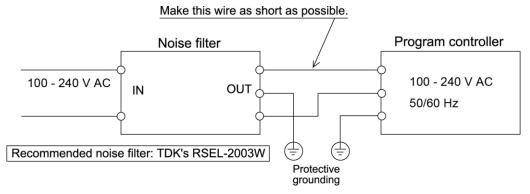


3-4. Wiring

In wiring operation, close attention should be paid to the following:

⚠CAUTION

- Make sure to disconnect this instrument from any power source during wiring operation to prevent an electric shock.
- Be certain that the protective conductor terminal () is properly grounded. Otherwise, an electric shock may result.
- To prevent an electric shock, don't touch wired terminals and other charged elements while they are being energized.
- ① In wiring operation, follow the terminal layout shown in Section 3-5 and the terminal arrangement in Section 3-6 and make sure to carry out the correct wiring.
- ② Use press-fit terminal which fits an M3.5 screw and has a width of 7 mm or less.
- ③ In case of thermocouple input, use a compensating cable compatible with the selected type of thermocouple.
- 4 In the case of R.T.D. input, the resistance of a single lead wire must be 5 Ω or less and the three wires must have the same resistance.
- (§) The input signal wire must not be accommodated with a high-voltage power cable in the same conduit or duct.
- © Shield wiring (single point grounding) is effective against static induction noise.
- Twisting the input wires at short and equal intervals is effective against electromagnetic induction noise.
- 8 In wiring for power supply, use a wire or cable whose performance is equal to or higher than the 600V vinyl insulated wire having a sectional area of 1 mm² or larger.
- **3** The wire for grounding must have a sectional area of 2 mm² or larger and must be grounded at a grounding resistance of 100Ω or less.
- © Clamp the screws of terminals firmly. Clamping torque: 1.0 N m (10kgf cm)
- 1 Countermeasure against lightning surge will be required for signal line over 30m.
- ① If the instrument appears to be easily affected by power supply noise, use a noise filter to prevent malfunctioning.
- (3) Mount the noise filter on the grounded panel and make wire connection between the noise filter output and the power line terminals of the controller as short as possible.



3-5. Terminal Layout

(Follow the terminal layout and terminal arrangement table shown below in your wiring operation.)

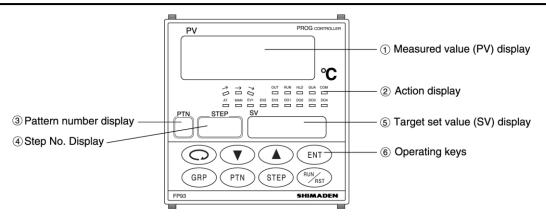
				. —				^ =====================================
*1	L TI	ERMINA	٩L	сом	1 1	+	21	/!\ 11k L
SPECIFICATION	23	24	25			A-output	ш	100-240VAC~
RS-232C	SG	SD	RD	DI1	2	-	- 22	12 50/60Hz 16VA
RS-485	SG	+	_				. —	
				DI2	3	[23	13
				DI3	4	*1 *1	24	+ 14 OUTPUT 4-20mA DC
				DI4	5	Ĺ	25	15) 0-10V DC DC 30mA 12V DC
			+ V/m	A DC	6	COM	2 6	16) 2A240VAC
					7	DO1	27	17) сом
				mV DC	8	DO2	28	18 EV1 1A240VAC
			<u> </u>		9	DO3	29	-00-19) 1A240VAC
				L	10	DO4	30	1A240VAC

3-6. Terminal Arrangement Table

Name of terminal	Description / Code	Terminal No.
Power supply	100–240VAC: L	11
	100–240V AC: N	12
Protective conductor	Protective grounding 🕒	13
Input	Voltage (V) Current (mA): +	6
	R.T.D.: A, thermocouple/Voltage (mV): +	7
	R.T.D.: B, thermocouple/Voltage (mV, V), Current (mA): –	9
	R.T.D.: B	10
Control output	Contact: COM, SSR drive voltage/Voltage/Current: +	14
	Contact: NO, SSR drive voltage/Voltage/Current: –	15
	Contact: NC	16
Event output	COM	17
	EV1	18
	EV2	19
	EV3	20
Analog output	+	21
(option)	_	22
Communication	SG	23
(option)	RS-232C: SD, RS-485: +	24
	RS-232C: RD, RS-485: –	25
External control input	COM	1
	DI1	2
	DI2	3
	DI3	4
	DI4	5
Status output (DO)	COM	26
(option)	DO1	27
	DO2	28
	DO3	29
	DO4	30

NOTE 1: With thermocouple, voltage, or current input, shorting across B and B terminal will cause an error. Leave terminal No.10 open. **NOTE 2**: With voltage (V) or current (mA) input, don't connect anything with terminal No.7. Any connection with it may cause problems with the instrument.

4. Names and Functions of Parts on Front Panel

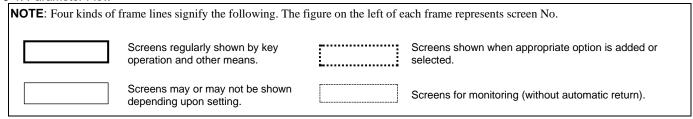


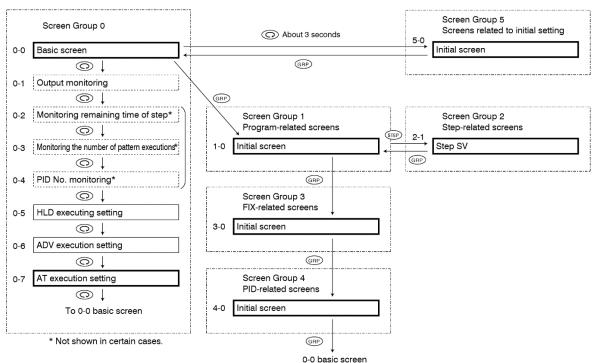
Name	Function
Measured value (PV) display	(1) Present measured value is displayed in the screen group 0. (red)(2) Type of parameter is shown on each parameter screen.
② Action display	 (1)
3 Pattern number display	(1) Pattern No. currently selected is displayed. (green)
Step No. Display	 (1) Step No. currently in execution is displayed. (green) (2) Step No. currently set in screen group 2 is displayed. (3) PID No. currently set in screen group 4 is displayed.
⑤ Target set value (SV) display	 (1) Target set value is displayed on the basic screen of screen group 0. (green) (2) Present output value is displayed in % on the output monitor screen of screen group 0. (3) Selected item and set value are displayed on each parameter screen.

Name	Function
Operating keys	(1) © (parameter) key
	Pressing this key on any screen calls the next screen onto display.
	• Pressing this key continuously for 3 seconds calls the initial screen of screen group 5.
	(2) (up) key
	Used to increase a numerical value on a numerical value setting screen.
	• Used to select an item on an item selection screen.
	(3) (down) key
	Used to decrease a numerical value on a numerical value setting screen.
	• Used to select an item on an item selection screen.
	(4) (entry) key
	• Used to register a set data changed by means of the or very key on each screen (the decimal
	point of the rightmost digit goes out).
	• When pressed for 3 seconds continuously on output (OUT) screen, this key switches between
	automatic output and manual output.
	(5) GRP (group) key
	• When pressed in the middle of setting in screen groups 1, 3, 4 or 5, the initial screen of the group is called onto display.
	• When pressed in the screen group 2, the initial screen of screen group 1 is called onto display.
	• When pressed on the basic screen, the display moves to screen group 1, screen group 3, screen group 4 and the basic screen in the order mentioned.
	• When pressed on the initial screen of screen group 5, the basic screen is called.
	(6) (pattern) key
	• When pressed during stop (RST) on the basic screen, a starting pattern can be selected. It is registered by pressing the we key
	• This key is used to move to other screen groups. For details, refer to "5-1. Parameter Flow" or
	"5-5. Explanation of Screen Group 0 and Setting."
	(7) (step) key
	• This key is used to move to other screen groups. For details, refer to "5-1. Parameter Flow" or
	"5-5. Explanation of Screen Group 0 and Setting."
	(8) (run/reset) key
	When pressed continuously for 3 seconds on the basic screen, execution (RUN) and stop (RST) are switched.
	• When pressed in any of screen groups 1–5, the preceding screen is returned onto display.

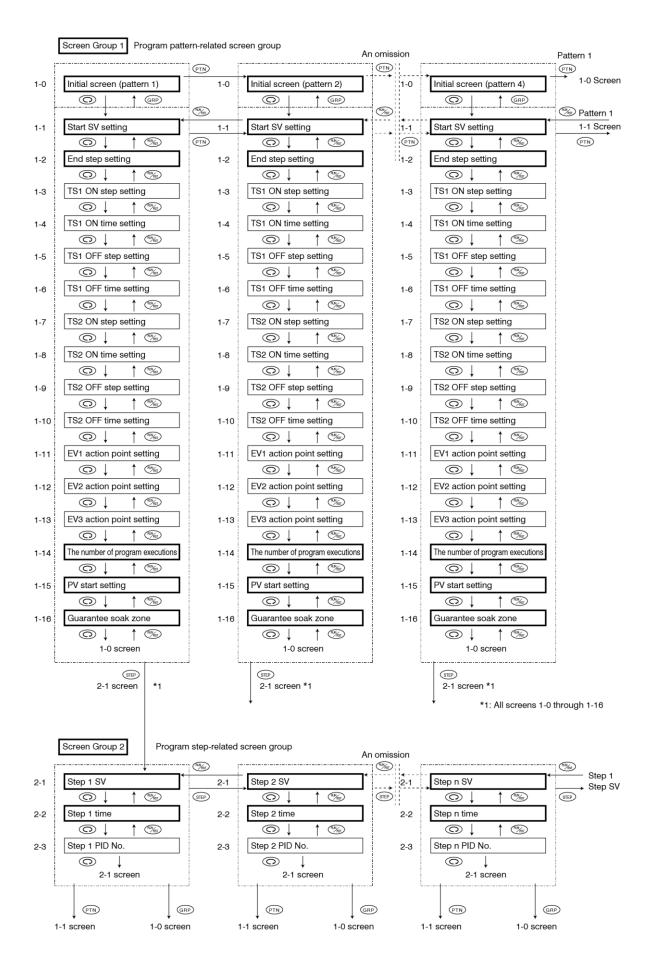
5. Explanation of Screens and Setting

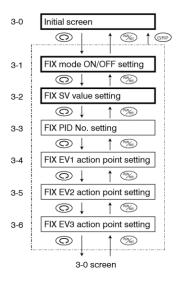
5-1. Parameter Flow

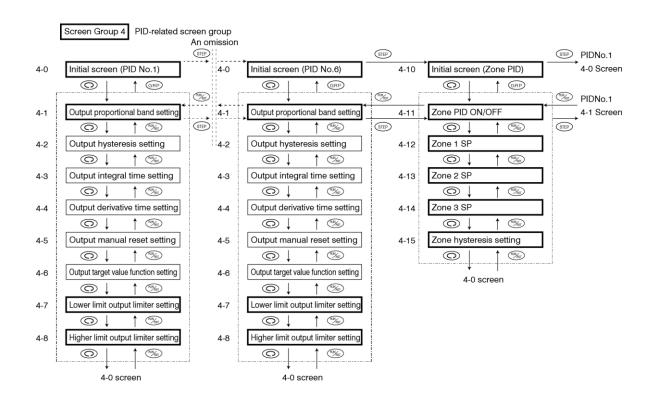


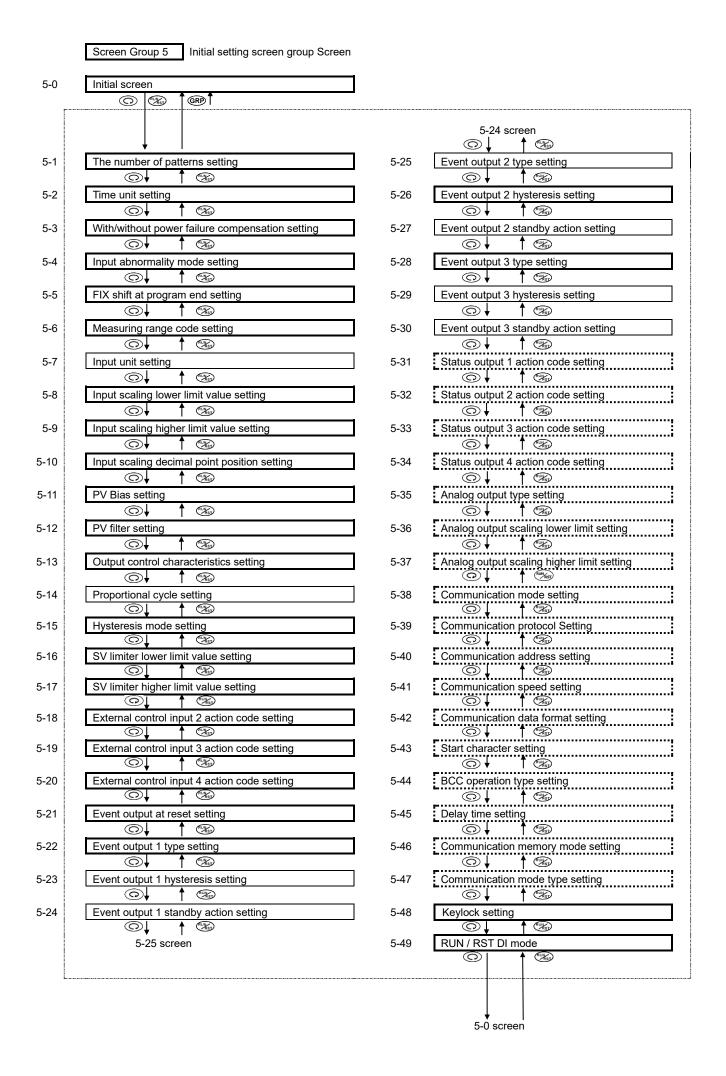


- (1) How to Move from Screen Group to Screen Group and Explanation of Screen Groups
- **NOTE 1**: To move among screen groups 0, 1, 3 and 4, press the Rey on the basic screen of screen group 0 or the initial screens of screen group 1, 3 or 4.
- NOTE 2: To move between screen groups 0 and 5, pressing the key for 3 seconds continuously on the basic screen of screen group 0 calls the initial screen of screen group 5, and pressing the key on the initial screen of screen group 5 calls the basic screen of screen group 0.
- **NOTE 3**: Pressing the we key in any screen group calls the next screen and pressing it on the last screen of a screen group calls the initial screen.
- NOTE 4: A key shown above and outside a chain line frame () surrounding each screen group means that you can move from any of the screen within the frame to a designated screen by pressing that key. (This applies to screen groups 1, 2, 3, 4 and 5.) Example: → Uscreen Group!
- **NOTE 5**: The screen group 1 has patterns 1–4. (One pattern has 16 setting screens.) The number of patterns is selectable (which is set on the 5-1 screen; the initial value is 4).
- **NOTE 6**: The screen group 2 has steps 1 to 64 (one step containing three setting screens). The number of steps is selectable (which is set on the 1-2 screen; the initial value is 16).
- **NOTE 7**: The screen group 4 has 6 PID Nos. (Each having 8 setting screens) and Zone PID.
- **NOTE 8**: Within a screen group, you can move from screen to screen by pressing an appropriate key indicated in screen sequences (which are shown in the following page on).



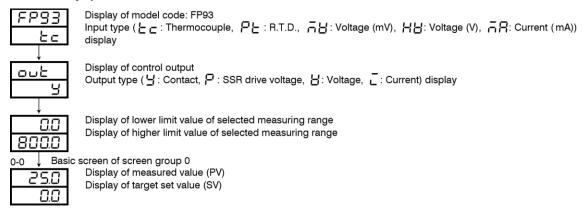






5-2. Application of Power and Display of Initial Screen

When power is applied, the initial screen and two screens are displayed successively, each for about 1 second as shown below. Then the basic screen is displayed.



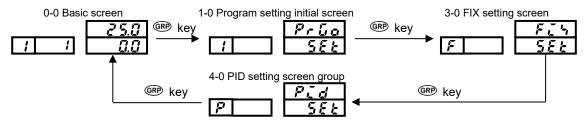
5-3. How to Change Screens

(1) How to Change Screen Groups 0-5

- Pressing the Rev key on the basic screen of screen group 0 calls the initial screen of screen group 1.
- Pressing the key on the basic screen of screen group 0 continuously for 3 seconds calls the initial screen of screen group 5.
- Pressing the EP key on any screen of screen group 1 calls the 2-1 screen of screen group 2.
- Pressing the GRP key on the initial screen of screen group 1 calls the initial screen of screen group 3.
- Pressing the (RP) key on any of the screens of screen group 2 calls the initial screen of screen group 1.
- Pressing the GRP key on the initial screen of screen group 3 calls the initial screen of screen group 4.
- Pressing the GRP key on the initial screen of screen group 4 calls the basic screen of screen group 0.
- Pressing the Rep key on the initial screen of screen group 5 calls the basic screen of screen group 0.
- Pressing the GRP key on any screen midway of screen group 0, 1, 3, 4 or 5 calls the initial screen of the screen group.
- Pressing the key on any screen midway of screen group 1, 2, 3, 4 or 5 calls the preceding screen.

 (Nevertheless, to return to the initial screen in screen group 1 or 4, you have to press the key or press the key continuously to move to the last screen of the group before returning to the initial screen.

① How to move among 0-4 screen groups

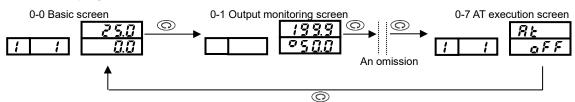


② How to move between screen group 0 and screen group 5



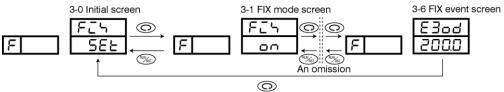
(2) How to Change Screen in Screen Group 0

Every time the key is pressed, the next screen is called, and the basic screen is called from the last screen.



(3) How to Change Screen in Screen Group 3

Every time the key is pressed, the next screen is called, and the basic screen is called from the last screen. Pressing the key calls the preceding screen.



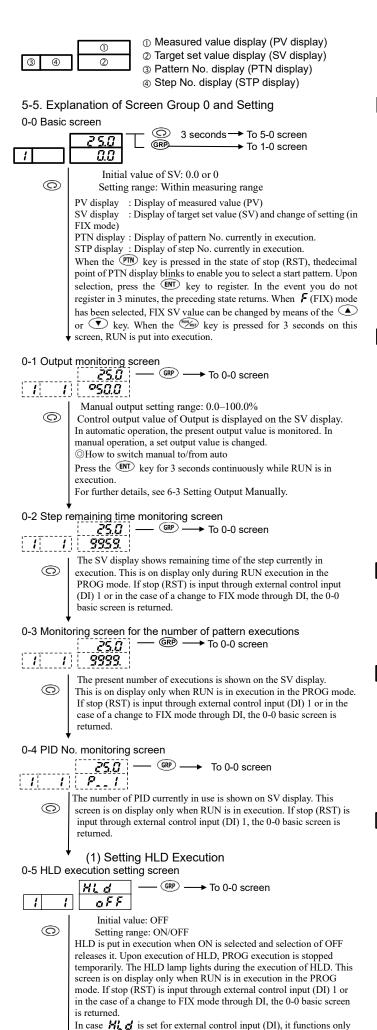
(4) How to Change Set Values (Data)

To change data on a screen which is called by pressing the key, use the tey, and register the changed data by pressing the key.

5-4. Before Starting Up

To begin with, check the wiring and carry out the following on the respective setting screens. (Factory-set items and items already set by equipment manufacturers need not be set here.)

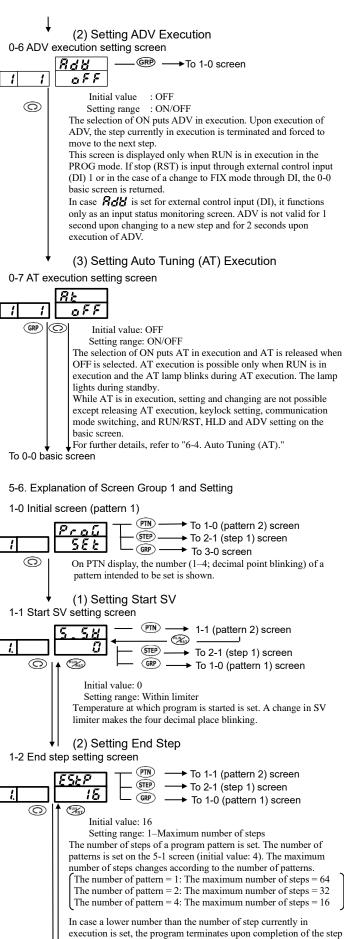
- (1) Checking Wiring
- : Check that the wiring to connected terminals is carried out properly. If the power line is erroneously connected to other terminals, it may cause burnout.
- (2) Applying power
- : Apply operating power. The controller is energized and the data display and other lamps light.
- (3) Setting Measuring Range
- : Select a code from the list of measuring range codes on the 5-6 Measuring range code setting screen. For current, voltage or mV input, lower/higher limit values and the position of decimal point of the contents of display in response to input signal should be set.
 - (Depending on a selected code, selection on the 5-7, 5-8 and 5-9 is also required.)
- (4) Setting Control Mode
- : In the case of ON-OFF (two-position) action, call the 4-1 Output proportional band setting screen of screen group 4 and select OFF for P and register it.
- (5) Setting Control Output Characteristic
 - : On the 5-13 Control output characteristics setting screen, select either RA (heating action) or DA (cooling action) for Act according to the purpose of use and register it.
- (6) Setting Other Data
- : Input necessary items such as program, event action and external input of program control. Record necessary data in "8. Record of Parameter Setting" and input them.
- (7) Note on Initialization upon Change of Data
 - : When a set data on measuring range code, input unit, higher/lower limit value of input scaling, event output type, analog output type or the like is changed, related data is initialized and resetting is required.



as an input status monitoring screen. ADV input is not valid during

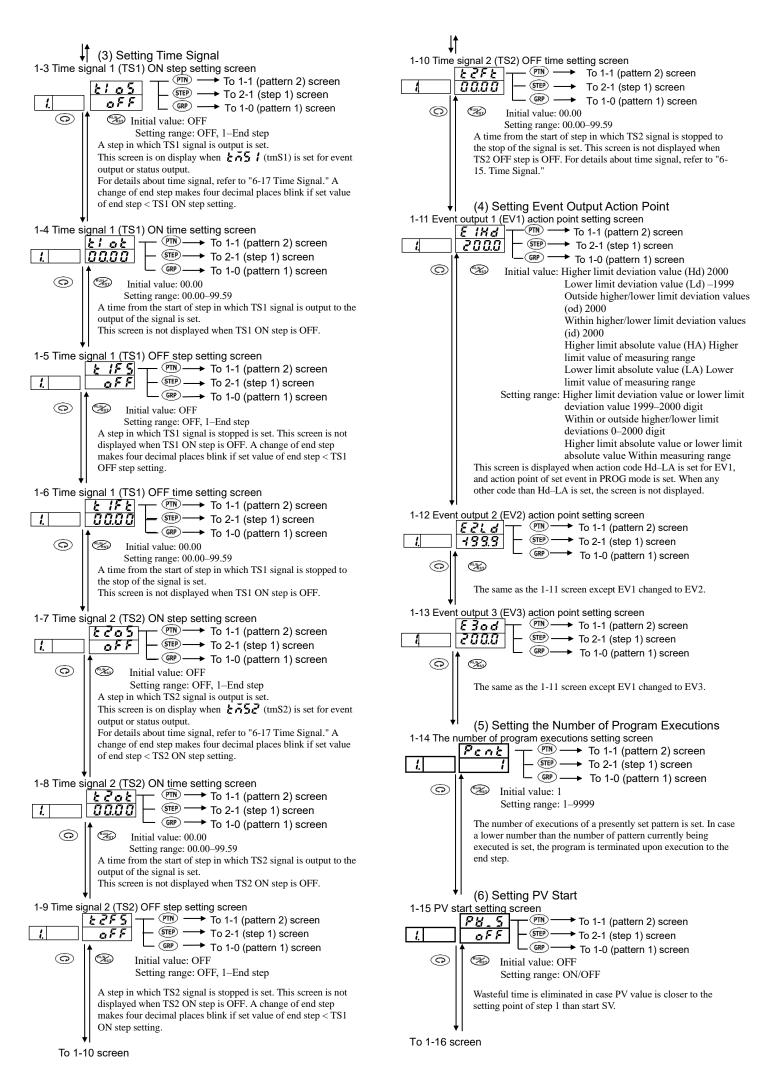
the execution of HLD.

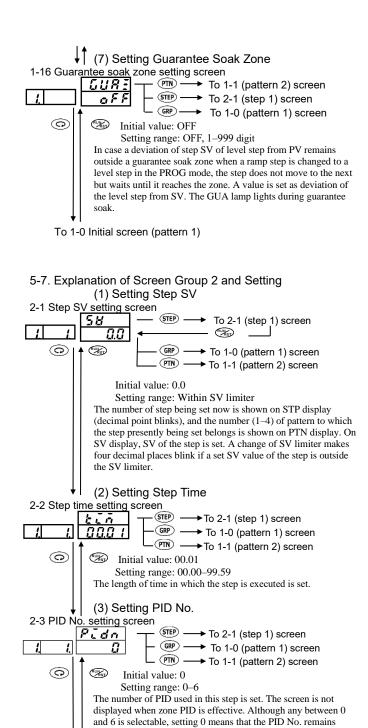
To 0-6 screen



currently being executed or moves to the initial step.

To 1-3 screen

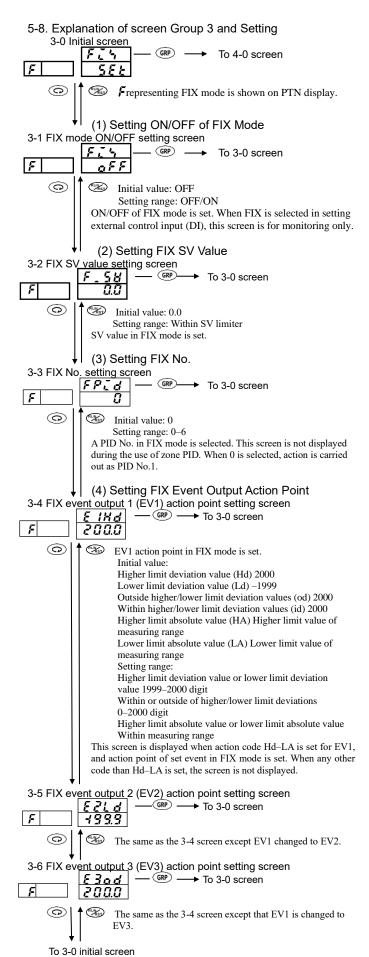


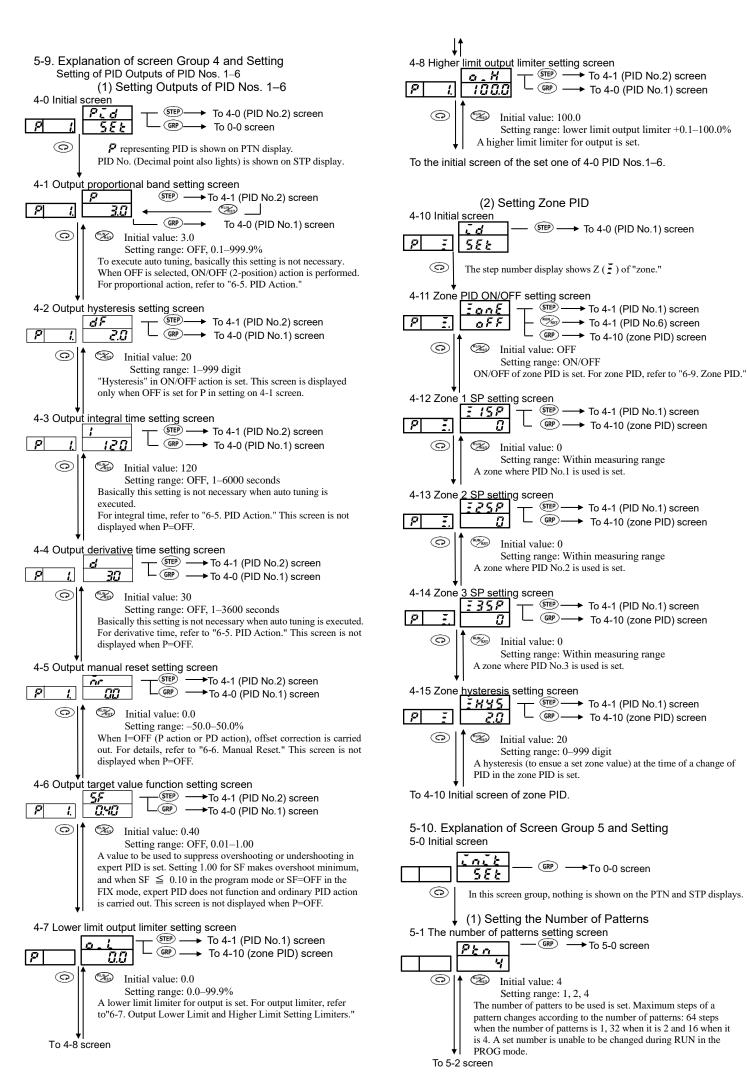


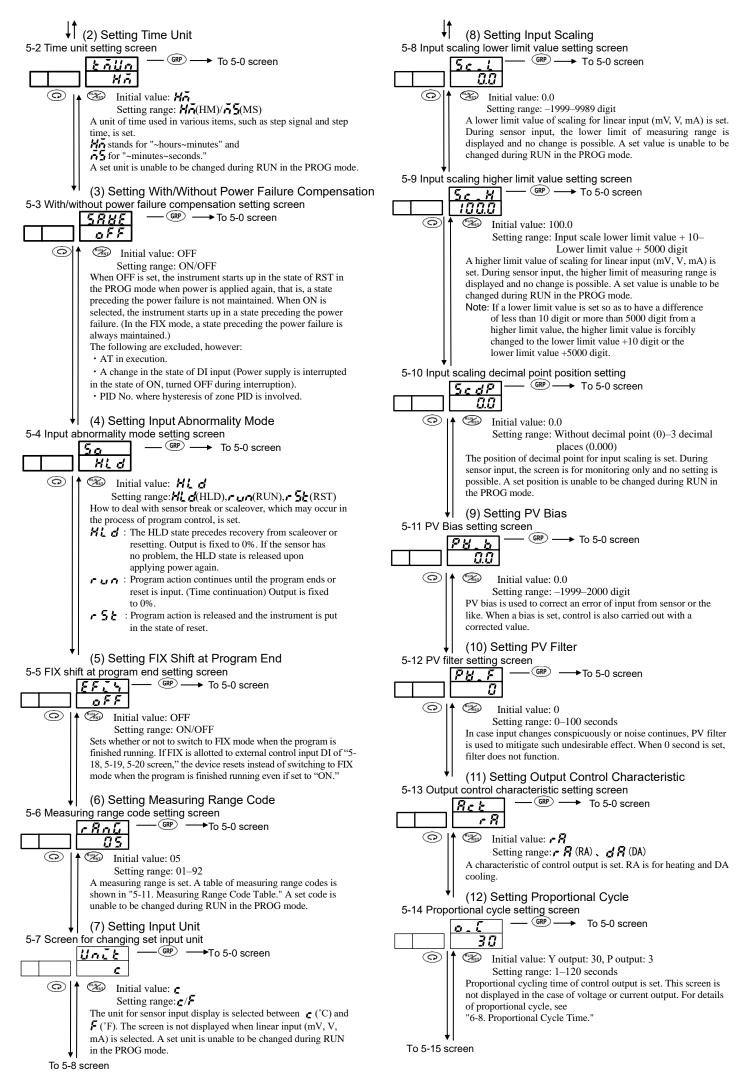
unchanged from that of the preceding step.

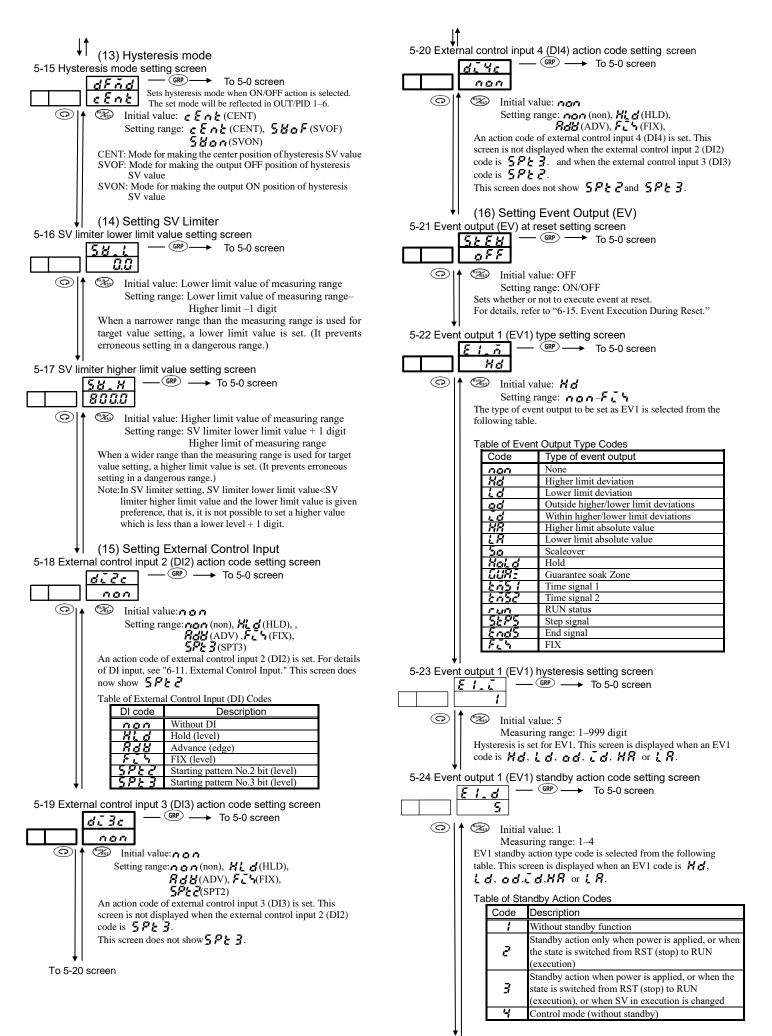
To 2-1 screen

Whenever 0 is selected, action is carried out as PID No.1.

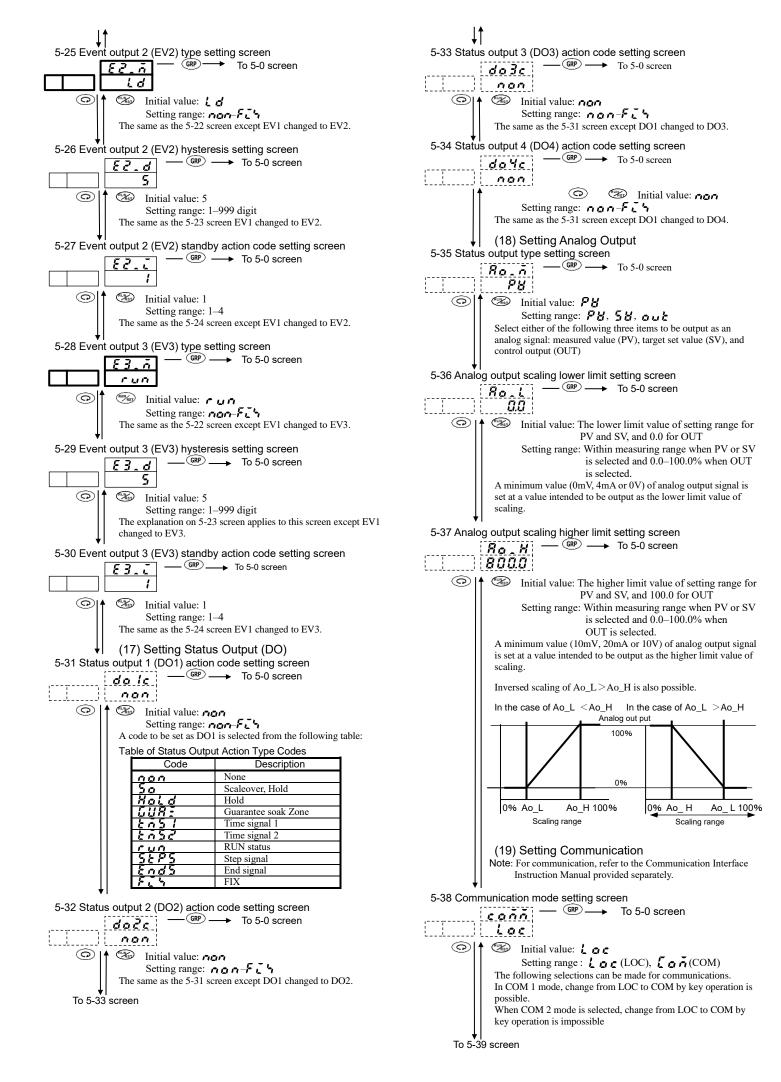


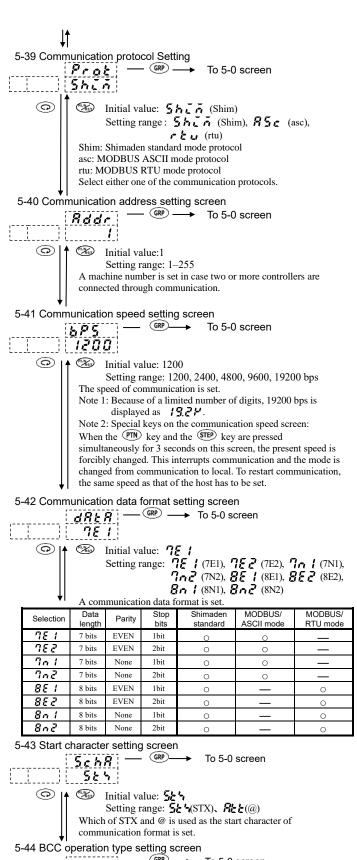






To 5-25 screen

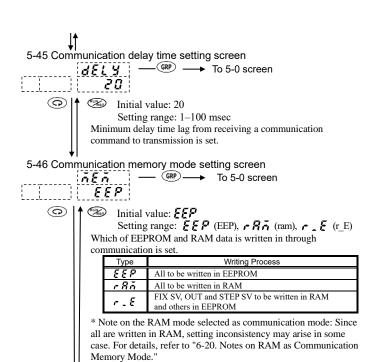




0	o ones i tone	2010	0		0	
5-43 Star	t character setting s	_				
,	achn `	GRP →	To 5-0	screen		
L	564					
0	Initial value Setting range		TX), <i>8</i> ;	· - (@)		
	Which of STX and communication for	l @ is used				
5-44 BCC operation type setting screen						
	b c c - (GRP —	To 5-0	screen		
<u></u>	Initial value	e: 1				
	Setting range	ge: 1–4				
	An operation type	for error de	tection B	BC check is se	lected from	
	the following table):				
	Type of Operation			Description		
	11					

	ne following table:				
Type of Operation		Description			
	1	Add operation from start character to text end character			
	2	2's complement after add operation from start character to text end character			
	3	Exclusive OR operation from 2nd character to text end character			
	ч	Without BCC operation			

To 5-45 screen



5-47 Communication mode type setting screen

Canr — GRP → To 5-0 screen ☐ |↑ ☐ Initial value: con_1

Setting range: con ! (COM1), con (COM2) Selects type of communication mode.

Set to COM1 if you want to enable key operation while writing by communication.

Communication mode types	cant	(COM1)	2000	(COM2)
Communication mode	COM	LOC	COM	LOC
Key operation	Available	Available	Not available	Available
Communication writing	Available	Available	Available	Not available

(20) Setting Keylock

5-48 Keylock setting screen - GRP → To 5-0 screen Lack

OFF (G) (U)KST Initial value: OFF

Setting range: OFF, 1, 2, 3 Items which should not be changed are locked. Data are unable to be changed on locked screens. Select OFF to release the lock.

l	Lock No.	Range to be locked				
l	oFF	Release of lock (All data allowed to be changed.)				
	1	Keylock of the screen groups 3, 4 and 5 (excluding communication mode and special keys on communication speed screen)				
	2	Keylock of screen groups 1, 2, 3, 4 and 5 (excluding communication mode and special keys on communication speed screen)				
	3	Keylock of all screens excluding RUN/RST on the basic screen, communication mode screen and special keys on communication speed screen)				

(21) Setting RUN / RST Di mode

5-49 RUN / RST DI mode screen

dīñd Ēdū ____ (GRP)_ To 5-0 screen (G) (U)KST Initial value: Edge Setting range: Edge, Level

Set whether to switch DI operation RUN/RST by DI level input or edge input.

Type.	Signal detectoin
EdG	Switch Run/Reset (Edge)
181	Switch Run/Reset (Level)

To 5-0 Initial screen

5-11. Measuring Range Codes Table

Select a measuring range from the following table.

Note: A change of a measuring range code will initialize all data related to the measuring range.

	Input type		C 1	Measu	Measuring range			
			Code	°C	°F			
		B *1	0 /	0–1800	0–3300			
		R	82	0-1700	0-3100			
	0	S	03	0-1700	0-3100			
			!!!! *2	-199.9-400.0	-300-750			
		K	05 08 07	0.0-800.0	0-1500			
	Thermocouple		08	0–1200	0–2200			
	1000	E	07	0–700	0–1300			
	ımc	J	08	0–600	0–1100			
	Llhe	T	#2	-199.9–200.0	-300–400			
		N	IÜ	0–1300	0–2300			
		PL II *3	11	0–1300	0–2300			
		C(WRe5-26)	12	0–2300	0-4200			
		U *4	13 *2	-199.9–200.0	-300–400			
		L *4	14	0–600	0–1100			
	D.		3 /	-200–600	-300–1100			
		Pt	32	-100.0–100.0	-150.0–200.0			
ındı			33	-50.0–50.0	-50.0–120.0			
Multi-input			34	0.0–200.0	0.0-400.0			
Æ	R.T.D.		35	-200–500	-300–1000			
_	124	JPt	38	-100.0–100.0	-150.0–200.0			
			37	-50.0–50.0	-50.0–120.0			
			38	0.0-200.0	0.0-400.0			
		-10–10mV	71		-			
		0-10mV	72					
		0-20mV	73					
		0-50mV	74	1				
	>	10-50mV	75	1				
	mV	0-100mV	78	Initial value: 0.0 to 100.0				
		-1–1V	8 /	Input scaling setting range: -1999 to 999	9 digit			
		0–1V	82	Span: 10 to 5000 digit				
		0-1 V 0-2 V	83	Position of decimal point: None, 1, 2 or 3	3 decimal places			
	>	0-2 V 0-5 V	84	Lower limit value < higher limit value				
			85	1				
		1–5V	88	1				
		0-10V	00	-				
n	ıA	0-20mA	9 /	-				
Tho		4–20mA	92	(WP of 26), HS/IEC				

Thermocouple B, R, S, K, E, J, T, N, C(WRe5-26): JIS/IEC R.T.D Pt100: JIS/IEC, JPt100: JIS

When not designated, factory-set measuring range is K thermocouple (0.0-800.0°C).

^{*1} Thermocouple B: Accuracy guarantee not applicable to 400° C or 750° Fand below.

^{*2} Thermocouple K, T, U: Accuracy of those whose readings are below -100°C is \pm (0.7% FS + 1digit).

^{*3} Thermocouple PLII: Platinel

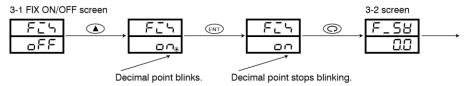
^{*4} Thermocouple U, L: DIN 43710

6 Operation and Functions

6-1. Using FIX Mode

FIX: Adjustment function without using the program function.

- ① Pressing the ② or ③ key on the 3-1 FIX ON/OFF screen turns OFF shown on the target value (SV) display to ON and the decimal point of the rightmost digit blinks. Then, press the ® ENT key, and the decimal point stops blinking to register the selection. (When OFF is set for FIX on this screen, the program mode turns ON.)
- 2 Pressing the key calls the next setting screen. Set a necessary item, if any.
- 3 When the display returns to the basic screen upon completion of setting, F is shown on the pattern number display and the FIX mode is ON.



6-2. Setting Target Value (SV) (FIX Mode)

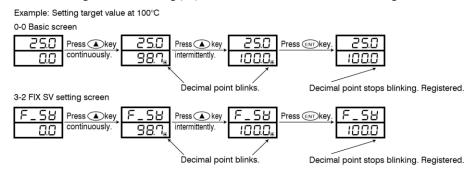
Setting on the basic screen

When the 🔊 or 🐨 key is pressed on the 0-0 basic screen, the decimal point of the rightmost digit blinks and the numerical value changes. The value keeps changing while either of the keys is being pressed. Once an intended value is reached, press the ENT key to register it. The registration of the data stops the blink of the decimal point.

② Setting on the SV setting screen

When the 🕟 or 🔨 key is pressed on the 3-2 FIX SV setting screen, the decimal point of the rightmost digit blinks and the numerical value changes. The value keeps changing while either of the keys is being pressed. Once an intended value is reached, press the 🖭 key to register it. The registration of the data stops the blink of the decimal point.

- * In the program mode, SV value is unable to be changed on the basic screen.
- * In the program mode, the 1-1 start SV setting screen and the 2-1 step SV setting screen should be used to set an SV.
- * No target value can be changed while auto tuning (AT) is in execution. It should be set after releasing AT.



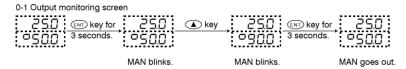
6-3. Setting Output Manually

For switching between auto and manual, press the we continuously for 3 seconds (in the state of RUN) on the output monitoring screen.

During manual output, the MAN lamp lights and it goes out when automatic output begins.

To set a target value, press the 🏖 or 🐨 key on the output monitoring screen. When the target value is reached, the setting completes. To release it, press the 🖭 key again for 3 seconds continuously, and automatic output is resumed.

- * Changing to manual output is not possible while auto tuning is in execution.
- ① 100% output is shown as •3939 and the decimal point of blinks.
- 2 When OFF is set for proportional band (P) in the case of contact output or SSR drive voltage output, the value of output is either 0.0% or 100.0%.
- 3 When OFF is set for proportional band (P) in the case of voltage output or current output, the output value becomes the lower or higher limit value of a set output limiter.



Supplementary Explanation of Monitoring Screen

The output monitoring screen (OUT) and automatic output/manual output:

- 1) When auto is changed to manual, output is in balanceless action and an output value immediately before the change is displayed. When manual is changed to auto, output is in bumpless action if it is bumpless. If it is outside the proportional band, however, the output is not in bumpless action.
- 2) In case power supply was turned OFF and power is applied again, control output is in the mode (either manual or auto) which was ON at the time of interruption of power supply.

NOTE: Even in the manual mode, it is possible to call another screen but it should be noted that control output is in the manual state. Blinking of the MAN action LED shows that the manual mode is ON.

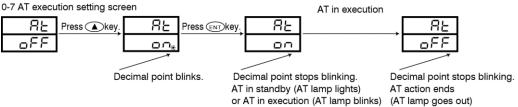
6.4. Auto Tuning (AT)

This is the function to automatically calculate and set P.I.D. values, i.e., parameters of PID control. The time required for calculation depends on the details of control.

1 Execution of AT

Pressing the key on the AT execution setting screen changes OFF shown on the target set value (SV) display to ON and the decimal point on the rightmost digit blinks. Upon pressing the key, the decimal point stops blinking and AT action begins. When the target set value stays in the inclined portions (portions indicated by the arrows of the action display), AT is in the state of standby (the AT lamp lights), and AT is executed while the target set value stays in the level portion (the AT lamp blinks).

While AT is in execution, the ON/OFF action of output is repeated several times in accordance with rise and fall of the measured value from the target value as the border and PID values are stored in an internal memory. Immediately when they are stored, control using these PID values begins and AT action ends. Then, the target set value display shows OFF and the AT lamp goes out. (In case there is AT still to be executed, it is put in the state of standby.)



② Release of AT in the Middle

To release AT in the middle, select OFF on the AT execution setting screen by the use of ③ key and press the @ key.

NOTE: In case AT is released in the middle, PID values are not changed.

- ③ Reasons Why AT Does Not Function
- 1) Control output is in manual mode.
- 2) The proportional band (P) of control output is OFF.
- 3) PV value (measured value) is in the state of scaleover.
- 4) On the keylock screen, No. 3 is selected. (AT is executed when it is turned ON before keylock setting.)
- 5) AT is suspended (RST).
- ① If the following conditions arise while AT is in execution, AT is released:
- 1) Output is at 0% or 100% continuously for 200 minutes.
- 2) PV value gets scaleover.
- 3) RST input is received.
- 4) AT is terminated by key operation or through communication.
- 5) AT of PID No. 1 through No. 6 (No. 3 in the case of zone) has completed.

6-5. PID Action

① P (Proportional action)

The ratio (%) of a range in which control output changes relatively to a measuring range is set. Output increases or decreases in proportion to difference between PV value and SV value. The narrower the proportional band, the larger a change in output, i.e., the stronger the proportional action. Nonetheless, an excessively narrow proportional band causes control to vibrate, resulting in control similar to ON-OFF action.

② I (Integral time)

This is the function to correct an offset (constant deviation) produced in proportional band. The longer the integral time, the weaker the correcting action, that is, reducing the integral time strengthens the correcting action but it may cause undulation of control results due to integral hunting.

3 D (Derivative time)

A change in control output is estimated and overshooting is suppressed to improve the stability of control. A longer derivative time strengthens derivative action but it may cause control results to vibrate.

6-6. Manual Reset

In PID action, an offset is corrected automatically by I, i.e., integration. When OFF is set for I, however, this correction is not carried out and so output is increased or decreased manually for correction. This method is called manual reset.

6-7. Output Lower Limit and Higher Limit Setting Limiters

- ① Output limiter means to limit a minimum or maximum value of control output and this function is effective in securing the lowest temperature or suppressing overshooting of control.
- ② Output limiter gives preference to a lower limit value. When a larger lower limit value than a higher limit value is set, the higher limit value is forced to become the lower limit value +0.1%. In other words, it is not possible to set a higher limit value which is less than a lower limit +0.1%.

6-8. Proportional Cycle Time

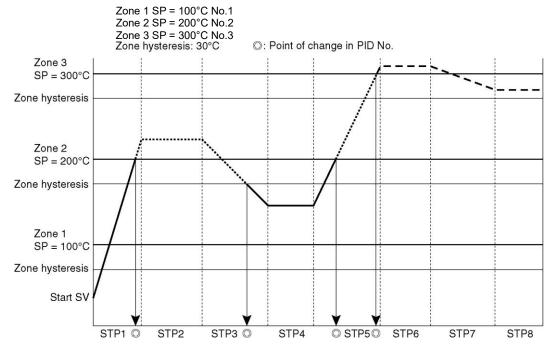
It can be set within a range from 1 to 120 seconds in the case of contact output or SSR drive voltage output. Proportional cycle time is ON time + OFF time within a proportional band.

6-9. Zone PID

The PID control of this instrument allows you to select and set the zone method.

In the zone PID control, a measuring range is divided into three types maximum, and control is carried out with PID No. which is selected automatically from an SV value set for each step.

Its basic action is: PID No. changes when control output becomes larger than an SP value or smaller than a zone hysteresis. An example of its action is diagramed below.



When above diagram shows SV as: Below $200^{\circ}C \rightarrow Action$ with PID No. 1 $200^{\circ}C-300^{\circ}C \rightarrow Action$ with PID No. 2 Above $300^{\circ}C \rightarrow Action$ with PID No. 3

When the setting of zone SP is changed as follows:

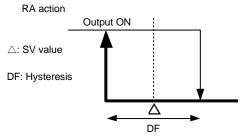
Zone 3 SP: 100°C Below 200°C → Action with PID No. 3 Zone 1 SP: 200°C 200°C–300°C → Action with PID No. 1 Zone 2 SP: 300°C Above 300°C → Action with PID No. 2

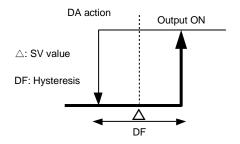
- * When the same zone SP value is set, the lowest number is used preferentially.
- * Even when a zone SP value in action is changed within a zone hysteresis, PID No. is not changed as long as output remains within the hysteresis.

6-10.Two-position action

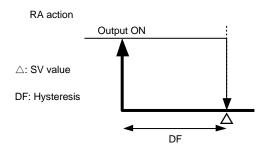
When conducting two-position action, frequent switching of output ON/OFF is prevented by utilizing hysteresis.

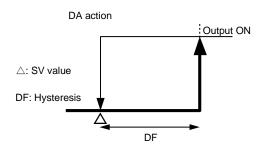
1) Hysteresis mode is CENT (F n):



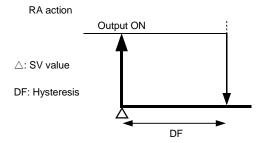


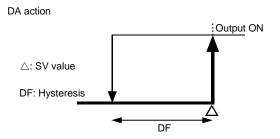
2) Hysteresis mode is SVOF (5 5 0 F):





3) Hysteresis mode is SVON (5 6 0 1):





6-11. External Control Input (DI)

The instrument has four DIs. DI is caused to function when any other item than non is set on the setting screen and external terminals are shorted. Action caused by each setting is described below:

① RUN/RST

Switching between RUN and RST. As this is assigned to DI1 fixedly, the setting is unable to be changed. Select edge input or level input on the 5-49 RUN/RST DI mode setting screen. Being edge input, RUN and RST are switched by shorting across terminals 1 and 2. Being level input, shorting across terminals 1 and 2 executes "RUN", and opening "RST".

O ADV

As on the 0-6 ADV execution screen, when executed, the present step comes to an end and is forced to proceed to the next step. Being edge input, ADV is executed every shorting across terminals.

3 HLD

As on the 0-5 HLD execution screen, when executed, the present step time is temporarily suspended and SV is fixed. Being level input, shorting across terminal puts HLD in execution and opening releases it. A change in step time, step SV, time signal ON/OFF time, etc. does not take effect until HLD is released.

4 FIX

As on the 3-1 FIX mode ON/OFF setting screen, when executed, the FIX mode turns ON. Being level input, shorting across terminals turns the FIX mode ON and opening releases it. If FIX is allotted to DI, status switches to reset when the program is finished running even if set to

"ON" by "5-5. FIX shift at program end setting screen."

A pattern No. at the start of program action is selected by 3 bits of DI2–DI4.

6 SPT2

A pattern No. at the start of program action is selected by 2 bits of DI3 and DI4. Being level input, shorting across terminals produces "1" and opening "0". Since the time for removing chattering of level input is

125msec, edge input action need to remain ON for 125msec or longer. If a number exceeding the number of patterns is input, a maximum number of patterns allowed to be set can be set.

For example: Where the number of patterns = 2 and DI input is 011, the number of start pattern is 2.

	DI4,	3,	2	
	0	0	0	Start with pattern 1
S	0	0	1	Start with pattern 1
Ρ	0	1	0	Start with pattern 2
Τ	0	1	1	Start with pattern 3
3	1	0	0	Start with pattern 4
	1	0	1	Start with pattern 4
	1	1	1	Start with pattern 4
	D	l4,	3	
S		0	0	Start with pattern 1
Ρ		0	1	Start with pattern 1
Т		1	0	Start with pattern 2
2		1	1	Start with pattern 3
	Not p	oss	ible	Start with pattern 4

6-12. Events

1 Deviation Alarm

An alarm action point is set by a deviation of measured value (PV) from target set value (SV).

For instance, to activate an alarm when measured value (PV) reaches 30 $^{\circ}$ C against SV value at 20 $^{\circ}$ C, higher limit deviation alarm is set at 10 $^{\circ}$ C. To activate alarm when measured value (PV) lowers below 30 $^{\circ}$ C in the case of an SV value at 100 $^{\circ}$ C, lower limit deviation alarm is set at -70 $^{\circ}$ C. This function is convenient for an alarm action point to follow deviations from target set value. The set range is -1999-2000 digit.

② Absolute Value Alarm

An alarm point is set by an absolute value.

For instance, to activate an alarm when measured value exceeds 50 °C, higher absolute value alarm is set at 50 °C. To activate an alarm when measured value lowers below 20 °C, lower absolute value alarm is set at 20 °C. Setting of higher or lower absolute value alarm is possible as long as it is within the measuring range.

Standby Action

In case 2 or 3 is set for event standby action, there is no event output upon applying power (or changing set value, or switching stop (RST) to execution (RUN)) even when measured value is within an event action area (an ON area). Event is output when it reaches the event action area again after it gets out of the event action area (gets in an OFF area).

Non-standby Action

In case event standby action is set for 1 and 4, an alarm is output when measured value gets in an action area upon applying power (or changing target set value).

© Control Mode (4 is set for standby action)

No event is output at the time of scaleover. The same applies to event standby.

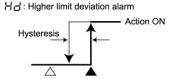
6-13. Setting Event Standby Action

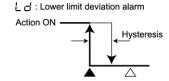
On 5-24 Event output 1 standby action code setting screen

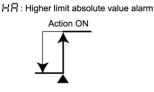
- ① When event output is used as an alarm, select from 1, 2 and 3 of the standby action code table.
- ② When event output is used for control, set 4 (control mode). In case 4 is selected, however, event output turns OFF at the time of input abnormality.
- 3 When 2 is selected, standby action functions only when power is applied.
- When 3 is selected, standby action functions when power is applied and when SV in execution is changed.
- (\$) When changed to 1 or 4 while standby action is going on, the standby action is released immediately.
- © Even when 2 or 3 is selected as standby action, it has no effect if PV value is outside the ON area of event action when power is applied or SV is changed.

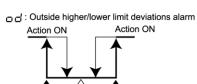
6-14. Diagrams of Alarm Actions Selectable as Event

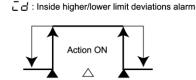
Diagrams of alarm actions to be selected for event output 1–3 are shown below:

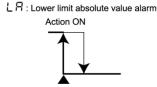












6-15. Event Execution During Reset

You can select whether or not to execute event at reset.

Event action during reset is specified on "5-21. Event output (EV) at reset setting screen."

A F F: Event output (excluding status output) is OFF.

: Event is output if event action conditions are satisfied.

Does not however include case where standby action is specified to control mode (see Code 4 of Table of Standby Action Codes of "5-24. Event output 1 (EV1) standby action code setting screen").

If event output type is status output, event is output during reset as well.

6-16. Event Output and Status Output Actions

The following nine items can be set for status output of "5-31, 5-32, 5-33 and 5-34" as well as event output:

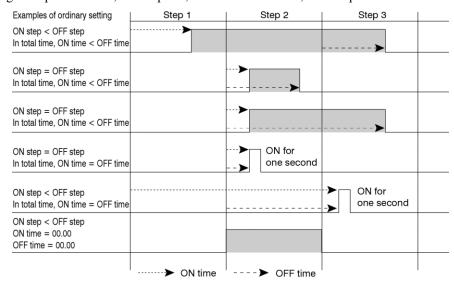
50	Scaleover	: To be output when measured value (PV) gets 10% above or below higher/lower limits of measuring range. (See the diagram on the right.) Action ON PV value — 110%						
HoLd	Hold	: To be output while HLD is set on DI input and 0-5 HLD execution setting and in communication in the PROG mode.						
GURE	Guarantee soak	: To be output while the state of guarantee remains in the PROG mode.						
EAS 1	Time signal 1	: To be output in the ON/OFF condition set in the time signal 1 setting (1-3, 1-4, 1-5 and 1-6) in the PROG						
		mode. For details, refer to "6-17. Time Signal."						
ŁĀ52	Time signal 2	: To be output in the ON/OFF condition set in the time signal 2 setting (1-7, 1-8, 1-9 and 1-10) in the						
		PROG mode. For details, refer to "6-17. Time Signal."						
Γ \cup Γ	RUN status	: To be output while RUN action is in execution.						
SEPS	Step signal	: To be output for one second when a step proceeds to another in the PROG mode.						
EndS	End signal	: To be output for one second when the last step ends in the PROG mode.						
FZS	FIX	: To be output while RUN action is in execution in the FIX mode.						

6-17. Time Signal

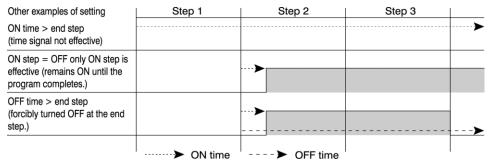
Time signal: Event output and status output can be produced for a designated period of time. Two points per pattern are equipped and ON step, OFF step, ON time and OFF time can be set individually.

- ① Time signal functions under the following conditions:
- 1) £55 for £552 is set as status output of event output.
- 2) OFF is not selected in Time signal ON step setting.
- 3) ON time is set within the end step.
- 4) In the total length of time elapsed since the start of program, ON time ≤ OFF time.
- In the case of ON step = OFF step and ON time = OFF time, time signal turns ON for one second.
- In the case of ON step < OFF step and ON time = OFF time in the total length of time elapsed since the start of program, time signal turns ON for one second.

(Example of setting: 1 step 10 minutes, ON step = 1, ON time 15 minutes, OFF step = 2 and OFF time 5 minutes)



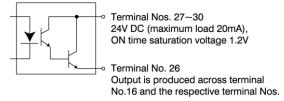
- * When a time signal-related parameter is changed during Hold (HLD), the change is not reflected until HLD is released.
- ② Reasons why time signal does not function (always OFF) (Time signal does not function in the following cases):
- 1) $\xi = 5$ or $\xi = 5$ is not set as status output of event output (including the case where these options are not added).
- 2) OFF is selected as Time signal ON step setting.
- 3) ON time exceeds the end step.
- 4) In the total length of time elapsed since the start of program, ON time > OFF time is set.
- 3 Other Matters related to Setting
- 1) The time of time signal is stopped during HLD and guarantee soak.
- 2) In case ON step and ON time are set and OFF step is OFF, once time signal turns ON, the end step also turns ON. (When one or more program executions are set, both remain ON until they are completed.)
- 3) In case OFF time is set beyond the end step, the end step is forcibly turned OFF. When ON step is the first step and 00:00 is set for ON time, it does not turn OFF.
- 4) In case ON time equals step time, it turns ON at the start of the next step.



5) When TS is assigned to a step of which the step time is 0, the action is the same as TS is assigned to the next step.

6-18. Status (DO) Output

This instrument has four status output as optional function (open collector output) points.



6-19. Auto Return Function

Should there be no key operation for 3 minutes on each screen except the monitoring screens (adjustment output, remaining time of step, the number of pattern executions, PID No.), the display returns automatically to the 0-0 basic screen of screen group 0 (auto return).

6-20. Notes on RAM as Communication Memory Mode

In case RAM is selected on the 5-46 communication memory mode, all set data are written in RAM. Care should be taken as this causes nonconformity of set data in a pattern like the following:

On the assumption that input range is 05 (K 0.0–800.0 °C),

- ① An event code is changed from higher limit deviation value to higher limit absolute value through communication (this change is recorded in RAM).
- ② Communication mode is changed from COM to LOC.
- ③ Event action point setting is changed from 800.0 to 700.0 by key operation. (Being in LOC mode, this change is recorded in EEPROM).
- Power supply is interrupted and power is applied again.
- © The event code recorded in RAM is cleared and higher limit deviation value is read from EEPROM.
- © Since the event action point set as 700.0 has been written in EEPROM, 700.0 is read.
- © Consequently, although the setting range of higher limit deviation value is actually –1999–2000 digit, an impossible value of 7000 digit is set.

To ensure proper use of the instrument, correct data must be set again.

7. Error Codes, Causes and Remedies

Screen display	Problem	Cause	Remedy
#### (HHHH)	Higher limit side scaleover	 Break of thermocouple input wiring Break of R.T.D. input A wiring Input measured value exceeded higher limit of measuring range by more than 10%. 	 Check thermocouple input wiring. If wiring has no problem, check and replace thermocouple. Check wire connection to R.T.D. terminal A. If wiring has no problem, replace R.T.D. For voltage or current input, check the transmitting unit of measured values. Check if set code of measuring range is the same as that of input signal.
LLLL (LLLL)	Lower limit side scaleover	Problem with wiring connection for input signal Input measured value fell from lower limit of measuring range by 10% Nonconformity of input range with input signal	Check wire connection for input signal. Check wiring of inversed polarity or break of wiring for measured value input. Check input range and input signal.
(b)	Break of R.T.D. input wiring	 Break of B More than one break of A, B and B 	Check R.T.D. input terminals A, A and B for breaks. If wiring has no problem, check and replace R.T.D.
(CJHH)	Higher limit side scaleover of cold junction (CJ) of thermocouple input	Ambient temperature of FP93 has exceeded 80°C.	 Reduce ambient temperature to the level provided in the environment conditions. In case ambient temperature has not exceeded 80°C, examine the instrument.
CJLL)	Lower limit side scaleover of cold junction (CJ) of thermocouple input	Ambient temperature of instrument has fallen to –20 °C or lower.	 ① Raise ambient temperature to the level provided in the environment conditions. ② In case ambient temperature has not fallen to -20°C, examine the instrument.

Note: When you find something wrong with the instrument, please re-read the instruction manual and examine the instrument again. For any problem with the product or further information, please contact our sales agent.

8. Record of Parameter Setting
(For convenience sake, recording set values and selected items is recommended.) The initial values are of Code 05 (K).

	Parameter (1/222)				
Screen No.	Parameter (Item)		Initial value	Setting/Selection	Remarks
0-0	Basic screen	0 (🗓)			
0-1	Output monitor				
0-2	Step remaining time				
0-3	Pattern execution number monitor				
0-4	PID No. monitor				
0-5	HLD execution setting	HLd. (#14)	off		
0-6	ADV execution setting	AdV. (🛱 🚜)	oFF		
0-7	AT execution setting	At. (#)	off		
1.0	laitial care as	ProG. (Prof.)	551		
1-0 1-1	Initial screen Start SV	ProG. (Pro 5) S_SV. (5.58)	5 <i>E k</i>		
1-1	End step	EStP. (£ 5 £ P)	8.8 18		
1-3	TS1 ON step	t1oS. (£ 1o 5)	o F F		
1-4	TS1 ON step	t1ot. (t lot)	00.00		
1-5	TS1 OFF step	t1FS. (£ /F 5)	0 0.0 0 0 F F		
1-6	TS1 OFF time	t1Ft. (£ !F £)	00.00		
1-7	TS2 ON step	t2oS. (¿ ¿ o 5)	0 0.0 0 0 F F		
1-7	TS2 ON time	t2ot. (¿ ¿ a k)	00.00		
1-9	TS2 OFF step	t2FS. (¿ ¿ f S)	0 0.0 0 0 F F		
1-10	TS2 OFF time	t2Ft. (¿ ¿ f 	00.00		
1-11	EV1 action point	E1**. (£ / **)	Hd: 2000 digit		
	★**includes action type.		Ld: -1999 digit od: 2000 digit		
1-12	EV2 action point ★**includes action type.	E2**. (£ £ **)	id: 2000 digit		
1-13	EV3 action point	E3**. (£ 3 **)	HA: Higher limit of measuring range		
1 10	★**includes action type.		LA: Lower limit of		
4.44			measuring range		
1-14	Program execution count	Pont. (Pent)	i - i		
1-15 1-16	PV start	PV_S. (PH_5)	0 F F		
1-10	Guarantee soak zone	GUAZ. ([] [] R E)	o F F		
2-1	Step SV	SV. (58)	0.0		
2-2	Step time	tim. (£ [~]	0001		
2-3	PID No.	Pidn. (<i>Pidn</i>)	0 0 0 0		
		(,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			
3-0	Initial screen	FiX. (/ 	586		
3-1	FIX ON/OFF	FiX. (F ,)	oFF		
3-2	FIX SV value	F_SV. (F_5 8)	0.0		
3-3	FIX PID No.	FPid. (FP , d)	<u> </u>		
3-4	EV1 action point	E1**. (£ / **)	Hd: 2000 digit		
3-4	★**includes action type.		Ld: -1999 digit		
3-5	EV2 action point	E2**. (£ ? **)	od: 2000 digit id: 2000 digit		
0.0	***includes action type.	[[] [] [] [] [] [] [] [] [] [HA: Higher limit of		
3-6	EV3 action point ★**includes action type.	E3**. (£ 3 **)	measuring range LA: Lower limit of		
			measuring range		
PID No. 1	T	Tau	T ==:	T	1
4-0	Initial screen	Pid. (P , d)	5 <i>E</i> Ł		
4-1	Output proportional band	P. (?)	3.0		
4-2	hysteresis	dF. (dF)	20 digit		
4-3	Output integral time	l. (;)	120		
4-4	Output derivative time	d. (d)	30		
4-5	Output manual reset	mr. (ñ r)	0.0		
			, 		
4-6	Output target value function	SF. (5 F)	0.40		
	Output target value function lower limit output limiter higher limit output limiter	SF. (5F) o_L. (a, L) o_H. (a, H)	0.40 0.0 100.0		

reen No No. 2	. Parameter (Item	,	Initial value	Setting/Selection	Remarks
4-0	Initial screen	Pid. (/ 1 d)	SEE		
4-1	Output proportional band	P. (🗗)	3.0		
4-2	hysteresis	dF. (dF)	20 digit		
4-3	Output integral time	l. (;)	120		
4-4	Output derivative time	d. (d)	30		
4-5	Output manual reset	mr. (<u>~</u> ~)	8.8		
4-6	Output target value function	SF. (5F)	0.40		
4-7	lower limit output limiter	o_L. (a . i .)	0.0		
4-8	higher limit output limiter	o_H. (<u>a</u> _ <u>H</u>)	10 0.0		
D No. 3		, , , , , , , , , , , , , , , , , , , ,			
4-0	Initial screen	Pid. (? [d)	5 <i>E</i> &		
4-1	Output proportional band	P. (?)	3.0		
4-2	hysteresis	dF. (d F)	20 digit		
4-3	Output integral time	l. (;)	120		
4-4	Output derivative time	d. (d)	30		
4-5	Output manual reset	mr. (/ / / /)	0.0		
4-6	Output target value function	SF. (5 F)	0.40		
4-7	lower limit output limiter	0_L. (a _ i _)	8.8		
4-8	higher limit output limiter	o_H. (a . H)	10 0.0		
D No. 4	1 -	, , ,			
4-0	Initial screen	Pid. (/ 7 / d)	5 <i>E E</i>		
4-1	Output proportional band	P. (🗗)	3.0		
4-2	hysteresis	dF. (dF)	20 digit		
4-3	Output integral time	l. (;)	120		
4-4	Output derivative time	d. (d)	30		
4-5	Output manual reset	mr. (/ / / /)	0.0		
4-6	Output target value function	SF. (5 <i>F</i>)	0.40		
4-7	lower limit output limiter	o_L. (a _ i_)	0.0		
4-8	higher limit output limiter	o_H. (a _ H)	10 0.0		
D No. 5	1 -	, ,			
4-0	Initial screen	Pid. (/ [] d)	5 <i>E</i> Ł		
4-1	Output proportional band	P. (?)	3.0		
4-2	hysteresis	dF. (dF)	20 digit		
4-3	Output integral time	l. (;)	120		
4-4	Output derivative time	d. (d)	30		
4-5	Output manual reset	mr. (n r)	0.0		
4-6	Output target value function	SF. (5 <i>F</i>)	0.40		
4-7	lower limit output limiter	o_L. (a . i.)	0.0		
4-8	higher limit output limiter	o_H. (a _ H)	100.0		
D No. 6		(= = · · · /		<u>l</u>	
4-0	Initial screen	Pid. (/ 7 / d)	5 <i>E</i> Ł		
4-1	Output proportional band	P. (?)	3.0		
4-2	hysteresis	dF. (d F)	20 digit		
4-3	Output integral time	l. (;)	120		
4-4	Output derivative time	d. (d)	30		
4-5	Output manual reset	mr. (~~ r)	0.0		
4-6	Output target value function	SF. (5 F)	0.40		
4-7	lower limit output limiter	o_L. (o _ i_)	0.0		
4-8	higher limit output limiter	o_H. (a _ H)	10 0.0		
ne PID	1 2	- (* * * * /	* 124 524 524	<u> </u>	
4-10	Initial screen	Pid. (/ L d)	SEE		
4-11	Zone ON/OFF	ZonE. (FanE)	off		
4-12	Zone 1 SP	Z1SP. (: /5?)	0 digit		
4-13	Zone 2 SP	Z2SP. (? ? 5 ?)	0 digit		
4-14	Zone 3 SP	Z3SP. (335 7)	0 digit		
4-15	Zone hysteresis	ZHYS. (FHY5)	20 digit		
7-10	Zono nyatoreala	21110. (27122)	20 digit		

Screen No.	Parameter (Item) / Sci	reen		Initial value	Setting/Selection	Remarks
5-0	Initial screen	init.	(LnLL)	586	Ŭ.	
5-1	Pattern No.	Ptn.	(Ptn)	<u> </u>		
5-2	Time unit	tmUn.	(ŁōUn)	HĀ		
5-3	With/without power failure compensation		(588E)	oFF		
5-4	Input abnormality mode	So.	(50)	HLd		
	,	Efix.				
5-5	FIX shift at program end		(EF. 5)	<u> </u>		
5-6	Measuring range code	rAnG.	(เกิดนี้)	<i>0</i> 5		
5-7	Input unit	Unit.	(Linit)	<u>c</u>		
5-8	Input scale lower limit value	Sc_L.	(50.4)	0.0		
5-9	Input scale higher limit value	Sc_H.	(5c.H)	100.0		
5-10	Input scale decimal point position	ScdP.	(5cd5)	0.0		
5-11	PV bias	PV_b.	(PB_b)	0 digit		
5-12	PV filter	PV_F.	(FH_F)	<u> </u>		
5-13	Output control characteristics	Act.	(Act)			
5-14	Proportional cycle	o_C.	(p_[)	Y: <u>∄</u> Ø P: <u>∄</u>		
5-15	Hysteresis mode	dFMd.	(d F n d)	cEnt		
5-16	Lower limit value of SV	SV_L.	(58.1)	00		
5-17	Higher limit value of SV	SV_H.	(58_H)	8000		
5-18	External control input 2 action code	di2c.	(d, c, c)	non		
5-19	External control input 3 action code	di3c.	(<u>d</u> , 3c)	non		
5-20	External control input 4 action code	di4c.	(<u>ch_'4c</u>)	non		
5-21	Event output at reset	StEV.	(<u>5 & E &</u>)	oFF		
5-22	EV1 output1 type	E1_m.	(<u>E 1.ñ</u>)	Hd		
5-23	EV1 output1 hysteresis	E1_d.	(E 1.d)	5 digit		
5-24	EV1 output1 standby action	E1_i.	(£ 1)			
5-25	EV2 output2 type	E2_m.	(\$2.5)	Ld		
5-26	EV2 output2 hysteresis	E2_d.	(<i>E2.d</i>)	5 digit		
5-27	EV2 output2 standby action	E2_i.	(
5-28	EV3 output3 type	E3_m.	(<i>E3.</i> n)	កណ្		
5-29	EV3 output3 hysteresis	E3_d.	(E3.d)	5 digit		
5-30	EV3 output3 standby action	E3_i.	(E3. .)	· · · · · · · · · · · · · · · · · · ·		
5-31	Status output 1 action code	do1c.	(do lc)	กดูก		
5-32	Status output 2 action code	do2c.	(<u>doč</u> c)	กดูก		
5-33	Status output 3 action code	do3c.	(da3c)	กดูก		
5-34	Status output 4 action code	do4c.	(do4c)	<u> </u>	-	
5-35	Analog output type Analog output scale lower limit	Ao_m.	(/	<u> </u>		
5-36	u i	Ao_L.	(Roll)			
5-37	Analog output scale higher limit Communication mode	Ao_H.	(Ro_H)			
5-38 5-39	Communication mode Communication protocol	comm.	(<u>conn</u>)	<u>Loc</u> Shīn	-	
5-39 5-40	Communication protocol Communication address	Addr.	(Prot) (Addr)	י אינייניב	-	
5-40	Communication address Communication speed	bPS.	(<i>b</i> 25)			
5-42	Communication speed Communication data format	dAtA.	(dAtA)	<u> </u>		
5-42	Start character	SchA.	(SchA)	<u> </u>		
5-44	BCC operation type	bcc.	(bcc)	<u> </u>		
5-45	Delay time	dELy.	(8ELY)	<u>20</u>		
5-46	Communication memory mode	mEm.	(<u>ň</u> ξň)	EEP		_
5-47	Communication mode type	ComK	(Lañr)	cañ l		
5-48	Keylock	LocK.	(Lact)	oFF		
5-49	RUN / RST DI mode	Dimd	(dind)	EdG		
			, =:=:/	'A 'A' 'A'		

	100%)															
Pattern No.																	
Start SV																	
Clart CV	90																
	30																
T	-																\vdash
The number of																	
steps																	
TS1 ON step	80																i
TS1 ON time	1																
	70																
TS1 OFF step	- 																-
101011 step																	\vdash
TO4 055 ::	-																
TS1 OFF time																	
	60																
TS2 ON step																	i
TS2 ON time	50																
TS2 OFF step	1																
132 OFF Step																	
	40																
	40																
TS2 OFF time																	
EV1 setting																	l
	30																
EV2 setting	1																
· ·																	
EV3 setting	20																
	<u> </u>																$\vdash \vdash \vdash$
The manual const	-																\vdash
The number of			-														
pattern executions																	
	10																
Guarantee soak																	
2 3																	
PV start	1																$\vdash \vdash \vdash$
r v Stall	_																
	0																
Step No.		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
SV (set value)																	
Time																	
PID No. (0~6)																	
																	

PID No.	1	2	3	4	5	6
Р						
1						
D						
Hysteresis						
MR						
Target value function						
Higher limit of output limiter						
Lower limit of output limiter						

Zone PID	
Zone PID ON/OFF	
Zone 1 SP	
Zone 2 SP	
Zone 3 SP	
Zone hysteresis	

[★] Copy these pages for your use as occasion demands.

9. Specifications

■ Display

• Display means Digital display: PV Red 7 segments LED 4 digits

> : SV Green 7 segments LED 4 digits : PTN Green 7 segments LED 1 digit : STEP Green 7 segments LED 2 digits

Green LED lamp indication Status display : OUT

: EV1-3 (3 points) Orange LED lamp indication Green LED lamp indication : AT : MAN Green LED lamp indication : COM Green LED lamp indication : DO1-4 (4 points) Green LED lamp indication : GUA Green LED lamp indication

Green LED lamp indication (blinks during FIX) : RUN

: HLD Green LED lamp indication : / "ascend" Green LED lamp indication → "level" Green LED lamp indication : Y "descend" Green LED lamp indication

• Display accuracy $:\pm (0.3\%FS + 1 \text{ digit})$, with restriction depending on measuring range, CJ error excluded.

• Display accuracy maintaining range : 23°C±5°C

• Display resolution : Differs by measuring range (0.001, 0.01, 0.1 and 1)

• Measured value display range : -10%–110% of measuring range (-210–680°C for Pt -200–600°C range)

• Display updating cycle : 0.25 second

 Input scaling : Possible during linear input (current and voltage)

(-1999-9999 digit, span 10-5000 digit, decimal point position variable)

■ Setting

• Local Setting : Operated by 8 keys (, , , , , , , , ,) on the front panel

• SV setting range : Same as measuring range (within setting limiter)

: Individual setting for higher and lower limits, any value is selectable within measuring range • Setting limiter

(Lower limit < Higher limit)

 Keylock : OFF, 1-3 (4 levels)

: °C or °F selectable for sensor input • Setting of unit

■ Input

: Selectable from multiple (TC, Pt, mV, V) and current (mA) • Type of input

• Thermocouple : Input impedance 500 kΩ minimum

> : External resistance tolerance 100 Ω maximum : Influence of lead wire tolerance 1.2 μ V/10 Ω

: Burnout function standard up scale

: Cold junction compensation accuracy Within the accuracy maintaining range ± 1 °C Ambient

temperature 5-45 °C ±2 °C

*1: For K, T and U thermocouples with indication values below -100 °C, ± (0.7%FS + 1 digit)

*2: Accuracy guarantee not applicable to B thermocouple below 400 °C or 750°F.

• R.T.D. : Normal current: 0.25 mA

: Lead wire tolerance 5 Ω maximum/wire (3 lead wires should have the same resistance.) Influence of lead wire tolerance (error in temperature)

0.3 °C maximum in the case of 5 Ω /wire 0.7° C maximum in the case of 10Ω /wire 1.6° C maximum in the case of 20 Ω /wire

 Voltage : Input impedance 500 kΩ minimum

• Current : mA to be taken care of by external resistor 250 Ω

• Sampling cycle : 0.25 second • PV filter : 0-100 seconds • PV bias : -1999-2000 digit

 Isolation : Not insulated from system and DI but insulated from others

■ Control

: Expert PID control with auto tuning function • Control mode

RA (heating)/DA (cooling) action

: Contact 1c 240V AC 2.5A (resistive load) 1.0A (inductive load) • Type of control output/rating

SSR drive voltage12V±1.5V DC (Maximum load current 30mA)

Current 4–20mA (Maximum load resistance 600 Ω) Voltage 0-10V (Maximum load current 2mA)

• Resolution : About 1/13000 Accuracy of output $\pm 1.0\%$ FS (5–100%)

 Hysteresis Mode :Select from the 3 modes (CENT mode, SVOF mode, SVON mode)

• Control output

Proportional band (P): OFF or 0.1-999.9% FS (ON-OFF action by OFF) Integral time (I) : OFF or 1-6000 seconds (P or PD action by OFF) Derivative time (D) : OFF or 1–3600 seconds (P or PI action by OFF)

Target value function: OFF or 0.01-1.00

ON/OFF hysteresis : 1–999 digit (enabled when P = OFF) : $\pm 50.0\%$ (Effective when I = OFF) Manual reset

Output limiter : Lower limit 0.0–99.9%, higher limit 0.1–100.0%

Proportional cycle : 1–120 seconds (when contact and SSR drive voltage output)

Manual control : 0.0−100.0% Setting resolution 0.1

• Control output characteristic : RA/DA to be set by front key

Isolation : Contact output insulated from all
 AO (analog output) not insulated from SSR drive voltage, current or voltage output but insulated

from others

■ External control input (DI)

• Number of input points : 4

• Type of input : Edge or level input (none, RUN/RST, HLD, ADV, FIX and start pattern No.)

DI1 fixed to RUN/RST for DI2-4, selectable from none, RUN/RST, HLD, ADV, FIX and start

pattern No.

Input rating
 Ivoltage 5V DC (0.5mA/1 input)
 Input holding time
 Minimum 0.125 seconds

• Isolation : Not insulated from input and system but insulated from others.

• Action input : No-voltage contact or open collector

■ Event output

• Contact output rating : Normal open (1a x 3 common) 240V AC 1A (resistive load)

• Action : ON-OFF action

• Hysteresis : 1–999 digit (during alarm output)

• Types : Selectable from the following 16 types respectively for EV1, EV2 and EV3

No selection, Higher limit deviation, Lower limit deviation, Outside higher/lower limit deviations, Within higher/lower limit deviations, Higher limit absolute value, Lower limit absolute value, Scaleover, Hold, Guarantee soak, Time signal (2 types), RUN status, step signal, End signal, FIX

• Event setting range

Absolute value alarm: Within measuring range

Deviation alarm: Higher limit deviation -1999-2000 digit, lower limit deviation -1999-2000 digit

Outside higher/lower limit deviations: $0-\overline{2}000$ digit Within higher/lower limit deviations: $0-\overline{2}000$ digit

• Standby action : Selectable from the following 4 types respectively for EV1, EV2 and EV3

: None, Standby 1 (standby only when power is applied), Standby 2 (standby when power is applied,

when SV in execution is changed, or when switching RST to RUN) and Standby 3

(input abnormality not output [Control mode])

• Output updating cycle : 0.25 second

• Isolation : Insulated from other inputs

■ Communication function (option)

• Type of communication : RS-232C or RS-485

• Communication system : RS-232C/3-line type half duplex system, RS-485/2-line type half duplex multi-drop (bus) system

• Synchronization system : Start-stop synchronization system

• Communication distance : RS-232C/Max. 15m, RS-485/Max. 500 m (depending on conditions)

• Communication address : 1–255

• Communication speed : 1200, 2400, 4800, 9600, 19200 bps

• Communication delay : 1–100 msec

 $\bullet \ \, \text{Communication memory mode} \qquad : \text{Selectable from EEP, rAm and r_E}$

• Communication protocol : Shimaden standard mode

 Data format
 : 7E1, 7E2, 7N1, 7N2, 8E1, 8E2, 8N1, 8N2

 Control code
 : STX_ETX_CR, STX_ETX_CRLF, @_:_CR

Checksum (BCC) : Add, Add two's cmp, XOR, None

Communication data : ASCII data

: MODBUS ASCII mode

Data format : 7E1, 7E2, 7N1, 7N2

Control code : CRLF
Checksum (BCC) : LRC check
Communication data : ASCII data
Function code : 03H, 06H

1)03H Reading of data 2)06H Writing of data

: MODBUS RTU mode

Data format : 8E1, 8E2, 8N1, 8N2

Control code : NON
Checksum (BCC) : CRC-16
Communication data : Binary data
Function code : 03H, 06H

1)03H Reading of data 2)06H Writing of data

• Communication mode type : Selectable from COM1 and COM2.

• Number of connectable instruments : 1 for RS-232C, 31 for RS-485 (Address setting 1–255)

• Isolation : insulated from other inputs and outputs

• Others : Start character and BCC operation method also selectable

■ Analog output (option)

• Number of output points : 1

• Type of analog output : Selectable from measured value, target value (SV in execution) and control output

• Output specification/rating : Current 4–20mA DC (Maximum load resistance 300 Ω) Voltage 0–10V DC (Maximum load

resistance 2mA) 0–10mV DC (Output resistance 10 Ω)

• Output accuracy : ±0.3% FS (Comprehensive accuracy when measured value is output ±0.6% FS)

• Scaling : Within measuring range or output range (inversed scaling possible)

Output resolution : About 1/26000
 Output updating cycle : 0.25 second

• Isolation : Not insulated from P.I.V. control output but insulated from others

■ Status output (DO) (option)
• Number of output points : 4

• Type of output : None, scaleover, hold, guarantee soak, time signal (2 types), RUN status, step signal, end signal, FIX

• Output specification/rating : Open collector darlington output, voltage 24V DC (maximum load current 20mA), saturation voltage

during status output ON 1.2V

• Output updating cycle : 0.25 second

• Isolation : Insulated from other inputs and outputs

■ Program

Number of patterns
 Maximum 4 (setting 1, 2 or 4 possible)
 Number of steps
 Maximum 16-64 (Total number of steps = 64)

Number of PID types : Maximum 6
 Number of zone PID types : Maximum 3
 Zone hysteresis : 0–999 digit

• Time setting : 0 hour 0 minute–99 hours 59 minutes or 0 minute 0 second–99 minutes 59 seconds/1 step

• Setting resolution : 1 minute or 1 second

• Accuracy of time $:\pm$ (set time \times 0.02% + 0.25 second)

• Setting for each step : SV, step time and PID No.

• Time signal : 2 outputs/pattern, to be set within time setting range

Number of pattern executions : Maximum 9999
 PV start : ON/OFF
 Guarantee soak : OFF, 1–999 digit

Hold : Front key input or external control input
 Advance : Front key input or external control input

• Power failure compensation : ON/OFF (guarantee not applicable to the period of time of step in which power failure occurs)

■ General specification

• Data storage : Non-volatile memory (EEPROM)

• Environmental conditions for instrument operation:

Temperature : -10–50 °C

Humidity : 90% RH or less (no dew condensation) Height : 2000m from the sea level or lower

Over voltage Category: II

Pollution Degree : 2 (IEC60664)
• Storage temperature : -20–65°C

Storage temperature : -20-65°C
 Supply voltage : 100-240V AC±10% 50/60Hz

24V AC/DC±10% (option)
• Input/noise removal ratio : 50 dB or higher in normal mode (50/60 Hz)

130 dB or higher in common mode (50/60 Hz)

• Insulation resistance : Between input/output terminals and power terminal 500V DC 20 M Ω or above

Between power terminal and ground terminal 500 V DC 20 $M\Omega$ or above

• Dielectric strength : Between input/output terminals and power terminal 3000 V AC/minute

Between power terminal and ground terminal 1500V AC/minute

• Power consumption : 16VA maximum

• Conformity with standards

Safety: IEC61010-1 and EN61010-1

EN IEC 61010-2-030

EMC: EN61326-1

Protective structure
 Only front panel has dust-proof and drip-proof structure equivalent to IP66.

(applies for thickness of 1.2–3.2 mm only)

• Material of case : PPE (equivalent to UL94V-1)

• External dimensions : $H96 \times W96 \times D111 \text{mm}$ (Panel depth: 100 mm)

Panel thickness
 Mounting dimensions
 Weight
 1.0-4.0 mm
 H92 × W92 mm
 Approximately 450 g

The contents of this manual are subject to change without notice.

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